

SIMA EXAMPLE

Turret moored FPSO

Valid from SIMA version 4.6





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Table of Contents

1	Introduction	1
2	About the Model	1
3	Results	2



1 Introduction

The example shows how an internal turret can be modelled for single-point mooring.

The floater consists of two bodies, FPSO and Turret. FPSO is a typical SIMO-type body that can freely move in 6-DOFs. Turret is a special SIMO-type body that was designed for fixed, prescribed, or articulated structures.

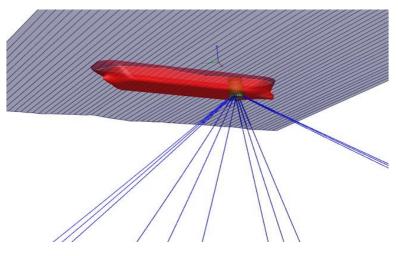


Figure 1-1 Turret moored FPSO

2 About the Model

Turret modelling can be easily achieved by using the turret type of articulated structure. Turret then will need a master body, that should be the FPSO in the example, to move following the motions of the FPSO body.

Catenary mooring lines are attached to the turret, and mooring forces are transferred to the FPSO. A Specified force is included in the Turret body to compensate the vertical downward force of the mooring lines.

Body	y 'Turi	et' in Tu	rretMoor	edFPSO			
lame:	Turr	et					
escriptio	n:					< >	
ype:	Pres	cribed		~			
	on and n X	nass γ	Z	Rx	Ry	Rz	Apply Gravity Force
	61.45	0.0	0.0	0.0	-0.0	0.0	
Accu	mulated	mass, volu	me and cente	r of gravity	(Calculated):		
Ac	c Mass	Acc Volu	me X	Y	Z		
	0.0		0.0	0.0	0.0	0.0	
Presc	ribed po	sition: Art	iculated strue	ture 🗸			
• A	rticulate	ed structur	e	_			
- F	Туре:	Turret		~			
	Master:	FPSO		~ 4	Ę		

Figure 2-1 Turret model in SIMA



To show the weathervane behavior, the FPSO is located with its initial yaw angle of 0 deg. facing the north. Longcrested irregular waves come from wave direction of 135 deg., bow-quartering sea. Static analysis is intentionally set as skipped to show the performance of the turret in the example.

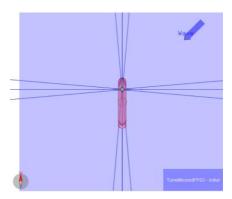


Figure 2-2 Initial condition

3 Results

In dynamic analysis, the FPSO starts to rotate and the yaw angle gets converged to 45 deg. that aligns well with the wave direction.

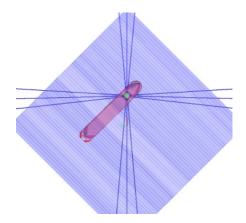


Figure 3-1 Snapshot at 10800 s. from dynamic analysis

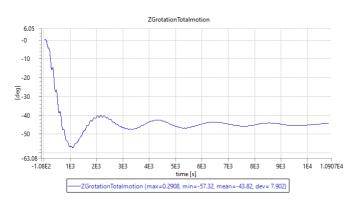


Figure 3-2 Yaw angle of FPSO



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