

Sesam example: JackUpLegContactProblem

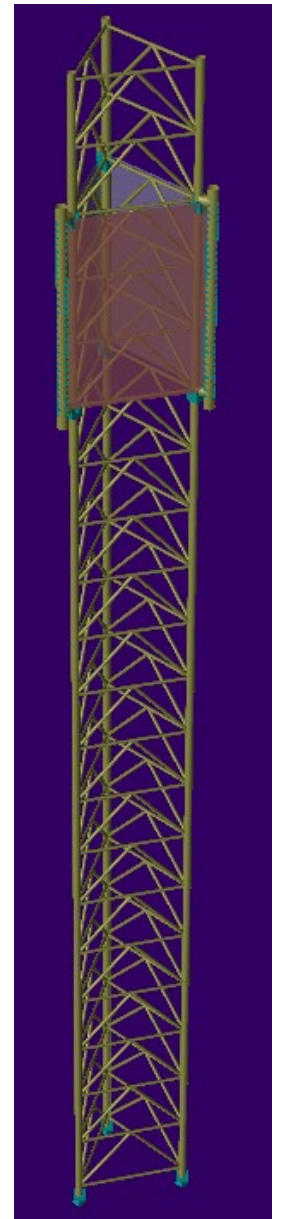
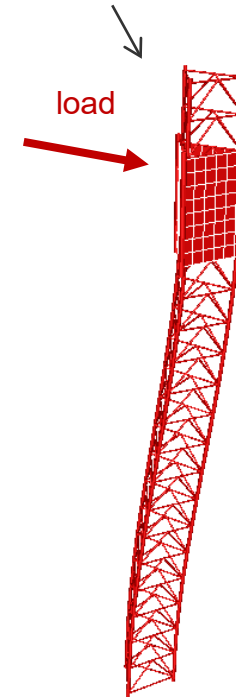
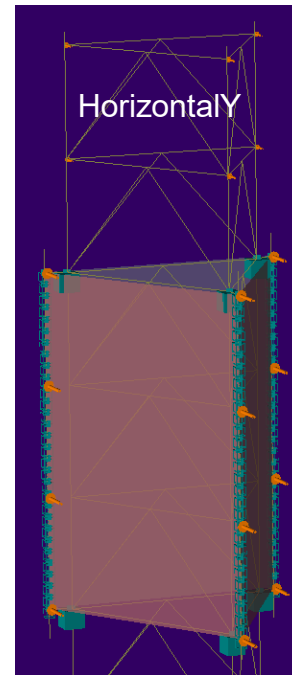
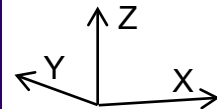
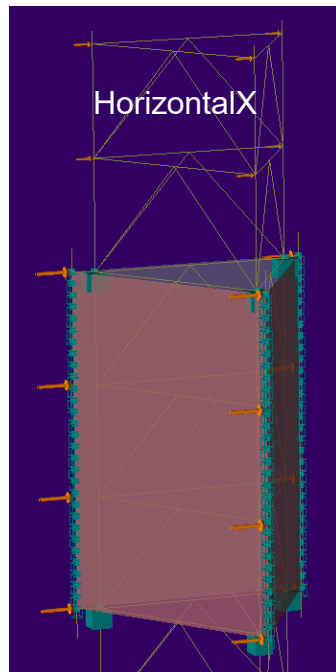
Using Presel and SestraGap to analyse contact problem between a simplified deck and a single jackup leg

Contact analysis controlled by GeniE

- Note that the present example is based on using the superelement assembly program Presel and the gap/contact analysis program SestraGap (that runs Sestra in the background).
 - This procedure is presently the method for contact analysis in Sesam offering the most general and advanced solution.
 - But as it requires some knowledge in Sesam programs additional to GeniE the user threshold is higher.
- GeniE version 8.3 offers simplified contact analysis which for many cases is adequate.
 - Being fully controlled by GeniE this method is much simpler than the procedure of the present example.
 - Go to a GeniE tutorial in advanced modelling and find an example of transportation analysis with contact problem to learn about contact analysis controlled by GeniE.

The model created in GeniE

- Single jackup leg with triangular prism as shown to the right
- Triangular prism illudes the jackup deck:
 - Density of the material is high so as to capture deck mass
 - Edges of the prism are fixed rotations about X and Y so as to achieve S-shaped deformation forced by deck
- Bottom of leg (3 points) three translations fixed
- Loads:
 1. HorizontalX
 2. HorizontalY
 3. Gravity



The analyses in Sestra

1. SingleSuperEILinearAnalysis

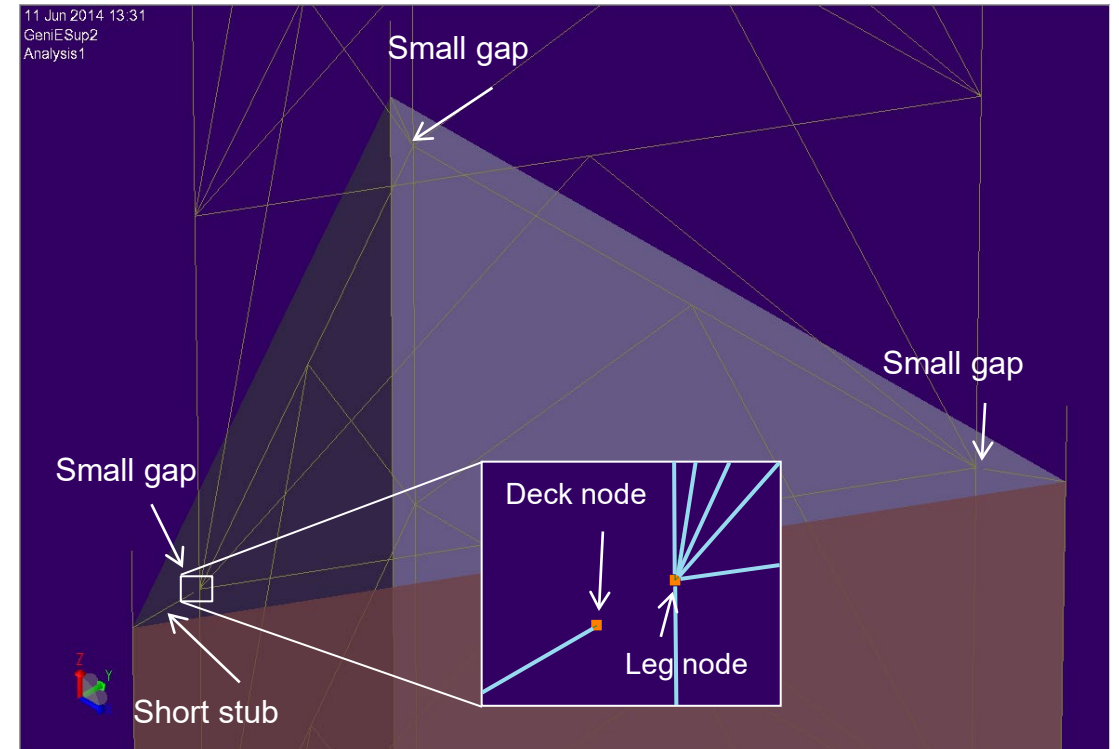
- Single model with no contact problem, i.e. full connection leg-deck

2. SingleSuperEIContactProblem – single model with contact definition leg-deck:

- Small gap between leg and short stub being part of deck prism
- Contact defined between leg node and deck node
- Difference in X and Y displacement between the two nodes is restricted to 5 cm:
 - $X_{\text{deck}} - 5\text{cm} < X_{\text{leg}} < X_{\text{deck}} + 5\text{cm}$
 - $Y_{\text{deck}} - 5\text{cm} < Y_{\text{leg}} < Y_{\text{deck}} + 5\text{cm}$
- Z displacements are set to be equal

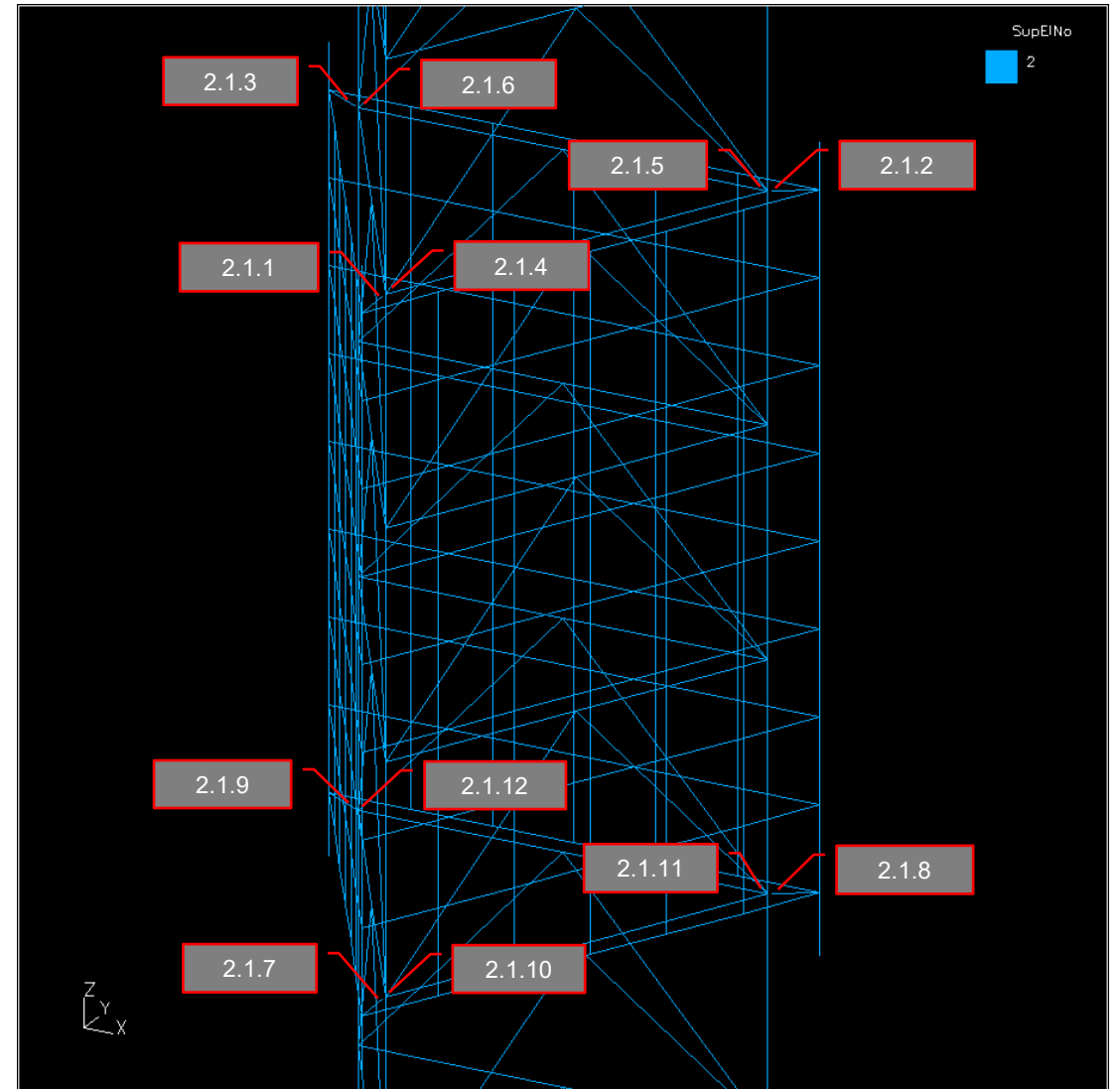
3. TwoSuperEIContactProblem

- As 2 above but leg and deck split into two superelements

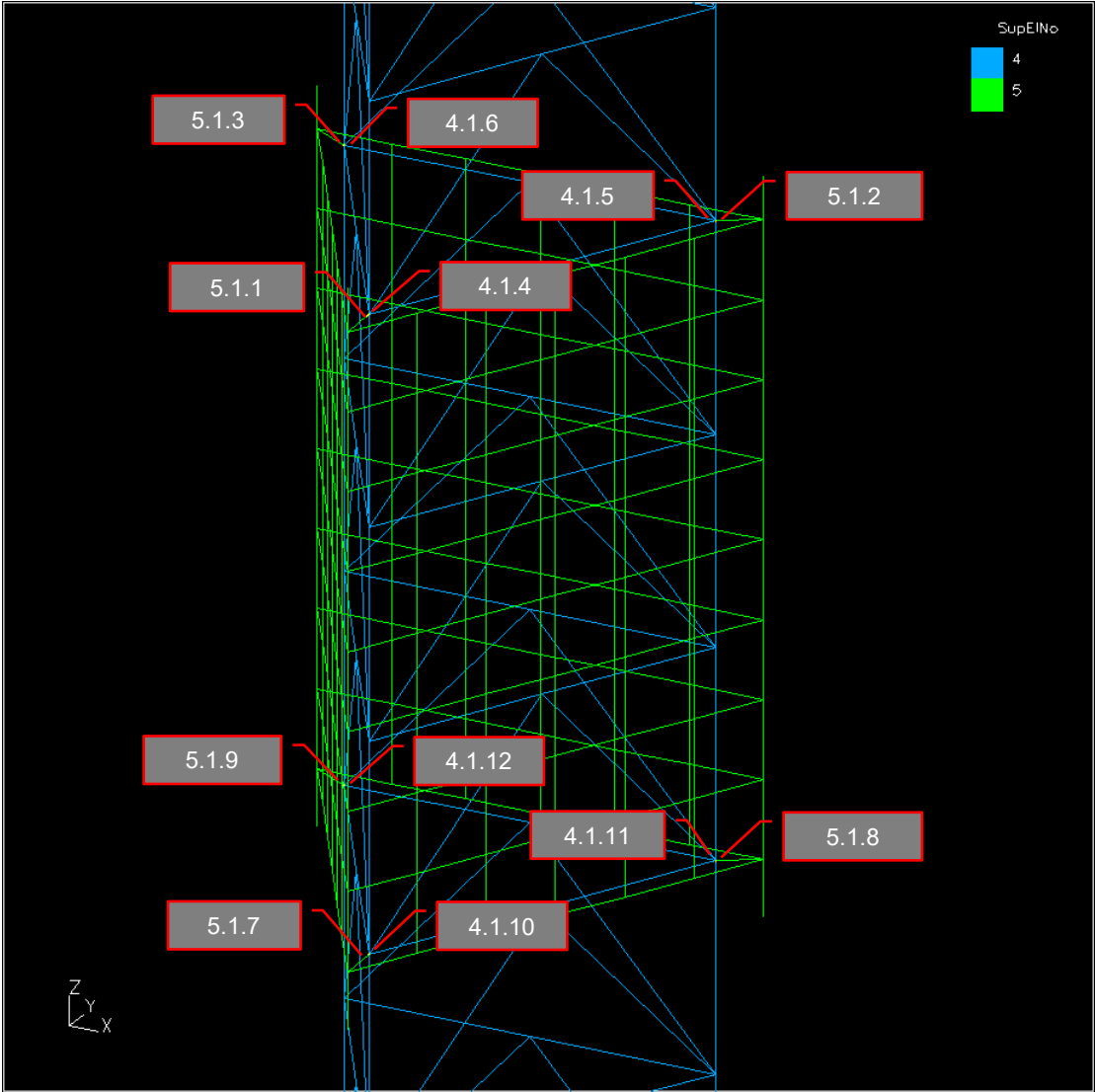


Presel: Node number triplets of SingleSuperEIContactProblem

- Contact information is defined in Presel referring to nodes
- Nodes are identified in Presel by node number triplets
- Node number triplet:
 - Superelement number
 - Superelement index (= 1 unless superelement is repeated)
 - Node number
- Displayed in Presel as three numbers separated by dots as shown to the right

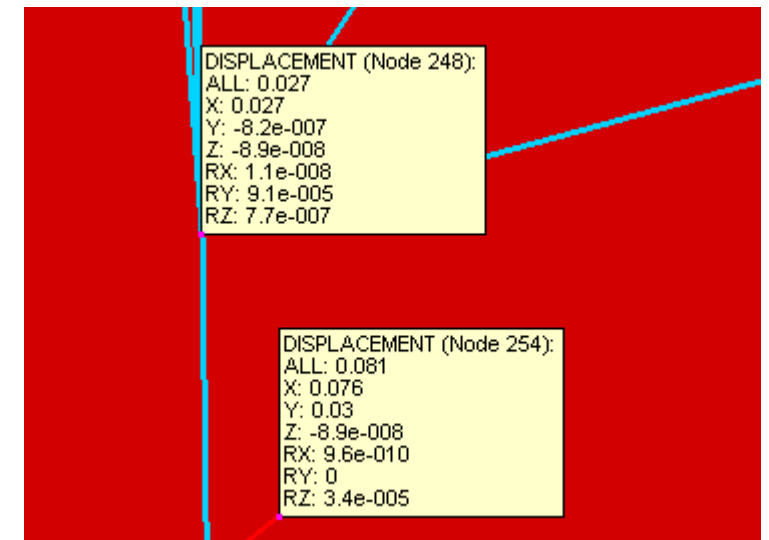
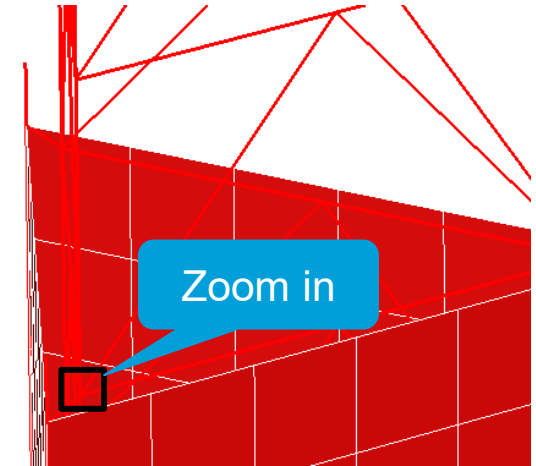


Presel: Node number triplets of TwoSuperEIContactProblem



Verify displacements of contact nodes in Xtract

- Switch off expanded beams
- Zoom in on one of the sets of contact nodes
- Select DISPLACEMENTS > ALL
- Show deformed model
- Set model deformation absolute scaling to 1
- Ctrl+click the contact nodes to label them
- Verify that difference in X and Y displacements for the two nodes is less than 0.05
- To the right is shown result case 1 for case SingleSuperEIContactProblem
- Verify for all contact nodes and all result cases for both cases



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